

# **MLFB-Ordering data**

6SL3210-1KE31-1AF1



Figure similar

Client order no. : Order no. : Offer no. : Remarks :

ltem no. :
Consignment no. :
Project :

Rated data		General tech. specifications		
Input		Power factor λ	0.9	90 0.95
Number of phases	3 AC	Offset factor cos φ	0.9	99
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.9	98
Line frequency	47 63 Hz	Sound pressure level (1m)	71	dB
Rated current (LO)	96.00 A	Power loss	1.5	55 kW
Rated current (HO)	85.00 A	Filter class (integrated)	Cla	iss A
Output		-		
Number of phases	3 AC	Ambient conditions		
Rated voltage	400 V	Cooling	Air coolin	g using an integrated fan
Rated power IEC 400V (LO)	55.00 kW	Cooling air requirement	0 083 m <sup>3</sup>	/s (2.931 ft³/s)
Rated power NEC 480V (LO)	60.00 hp	Installation altitude		
Rated power IEC 400V (HO)	45.00 kW		1000 m (:	3280.84 ft)
Rated power NEC 480V (HO)	50.00 hp	Ambient temperature		
Rated current (IN)	103.00 A	Operation		°C (-4 104 °F)
Rated current (LO)	103.00 A	Transport		°C (-40 158 °F)
Rated current (HO)	83.00 A	Storage	-40 70	°C (-40 158 °F)
Max. output current	165.00 A	Relative humidity		
Pulse frequency	4 kHz	Max. operation	95 % RH,	condensation not permitted
Output frequency for vector control	0 240 Hz			
		Closed-loop co	ontrol tec	hniques
Output frequency for V/f control	0 550 Hz	V/f linear / square-law / paramete	erizable	Yes
		V/f with flux current control (FCC	<b>.</b> )	Yes
Overload capability		V/f ECO linear / square-law		Yes
Low Overload (LO)		Sensorless vector control		Yes
150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time		Vector control, with sensor		No
		Encoderless torque control		No
High Overload (HO) 200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a		Torque control, with encoder		No

300 s cycle time



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Mechanical data		Figure simila		
Degree of protection         IP20 / UL open type				
Size	FSE	Communication	PROFINET, EtherNet/IP	
		Connections		
Net weight	28.50 kg (62.83 lb)	Signal cable		
Width	275 mm (10.83 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)	
Height	551 mm (21.69 in)	Line side		
Depth	237 mm (9.33 in)	Version	screw-type terminal	
Inputs / outputs		Conductor cross-section	25.00 70.00 mm² (AWG 4 AWG -1	
tandard digital inputs		Motor end		
Number	6	Version	Screw-type terminals	
Switching level: 0→1	11 V	Conductor cross-section	25.00 70.00 mm² (AWG 4 AWG -1	
Switching level: 1→0	5 V	DC link (for braking resistor)		
Max. inrush current	15 mA	Version	Screw-type terminals	
ail-safe digital inputs		Conductor cross-section	25.00 70.00 mm² (AWG 4 AWG -1	
Number	1	Line length, max.	10 m (32.81 ft)	
Digital outputs		PE connection		
Number as relay changeover contact	1	Max. motor cable length	Screw-type terminals	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	200 m (656.17 ft)	
Number as transistor	1	Unshielded	300 m (984.25 ft)	
Output (resistive load)	DC 30 V, 0.5 A	Standards		
Analog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
Number	1 (Differential input)			
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Voltag Directive 2006/95/EC	
witching threshold as digital in	out			
0→1	4 V			
1→0	1.6 V			
nalog outputs				
Number	1 (Non-isolated output)			
TC/ KTY interface				
1 motor temperature sensor input, senso	rs that can be connected. DTC KTV			

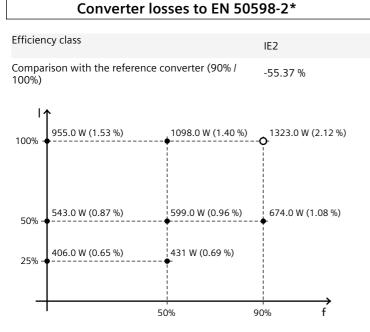
1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^\circ\mathrm{C}$ 



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The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values